# SECURE MALICIOUS NODE ATTACK IN MANET BY USING ADVANCED CO-OPERATIVE BAIT DETECTION

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**Abstract:**

Wireless networks are computer networks that are not connected by cables of any kind. The utilization of wireless network allows enterprises to avoid the costly process of introducing cables into buildings or as a connection association between completely different equipment locations. Wireless networks are at risk of completely different variety of attacks. MANET is the mobile wireless network that operates independently without any special hardware needs. A detection scheme called the Advanced cooperative bait detection scheme (ACBDS) is proposed that aims at detecting and preventing malicious nodes by launching rushing and black hole attacks to collaborate in MANETs environment. To resolve this issue AODV protocol is used enhancing the performance of the MANETs environment. Proposed system helps in defending against the black hole attack and rushing attacks without any special hardware requirements.

**KEYWORDS**: Malicious, Rushing Attack, Blackhole Attack, Collaborative Detection.

## 1. INTRODUCTION

A mobile adhoc network (MANET) may be a self-configuring network of mobile routers and associated hosts connected via wireless links. These routers are free to move and organize themselves in a random manner. Thus, this wireless topology may change rapidly and unpredictably. The primary challenge in building a MANET is equipping each device to continuously maintain the information required to properly route traffic. Such a network may operate in a standalone fashion, or may be connected to the larger Internet. They may contain one or multiple and different transceivers between nodes. This results in a highly dynamic, autonomous topology. Minimal configuration and quick deployment make adhoc networks suitable for emergency situations like natural or human-induced disasters, military conflicts, emergency medical situations etc. In black hole attack, a malicious node uses its routing protocol in order to advertise itself for having the shortest path to the destination node or to the packet it wants to intercept. This hostile node advertises its availability of fresh routes irrespective of checking its routing table. In this way attacker node will invariably have the provision in replying to the route request and so intercept the data packet and retain it. In protocol based on flooding, the malicious node reply will be received by the requesting node before the reception of reply from actual node; hence a malicious and forged route is created. When this route is establish, now it's up to the node whether or not to drop all the packets or forward it to the unknown address. The method however malicious node fits within the data routes varies. In this type of attack, an adversary node which receives a Route Request packet from the source node floods the packet quickly throughout the network before other nodes that conjointly receive the same Route Request packet will react. Nodes

that receive the legitimate Route Request packets assume those packets to be duplicates of the packet already received through the adversary node and hence discard those packets. Any route discovered by the source node would.

## 2. RELATED WORK

Tsou et al. (2011) presented a mechanism to find malicious nodes launching black/gray hole attacks and cooperative black hole attacks, known as Cooperative Bait Detection Scheme (CBDS). It integrates the proactive and reactive defense architectures, and randomly cooperates with a random adjacent node. By using the address of the adjacent node as the bait destination address, it baits malicious nodes to reply RREP and detects the malicious nodes by the proposed reverse tracing program and consequently prevents their attacks. Deng et al. (2002) proposed a solution for the black hole problem for adhoc on-demand distance vector routing protocol. One limitation of the proposed method is that it works based on an assumption that malicious nodes do not work as a group, although this could happen during a real scenario and presently gazing this downside of team attacks. Xue and Nahrstedt (2004) proposed a new routing service named best-effort fault-tolerant routing (BFTR). The design goal of BFTR is to provide packet routing service with high delivery ratio and low overhead in presence of misbehaving nodes. Instead of identifying whether a path is good or bad, i.e., whether it contains any misbehaving node, BFTR evaluates the routing feasibility of a path by its end-to-end performance (e.g. packet delivery ratio and delay). By continuously observing the routing performance, BFTR dynamically routes packets via the most feasible path. BFTR provides an efficient and uniform resolution for a broad range of node misbehaviors with very few security assumptions. The BFTR algorithm is evaluated through both analysis and extensive simulations. The results show that BFTR greatly improves the adhoc routing performance in the presence of misbehaving nodes. Baadache and Belmehdi (2010) proposed that after having specified the black hole attack, a secure mechanism, which consists in checking the good forwarding of packets by an intermediate node. The proposed solution avoids the black hole and the cooperative black hole attacks. Evaluation metrics were considered in simulation to show the effectiveness of the suggested solution.

## 3. PROPOSED SYSTEM

The proposed methodology presents a detection scheme called the cooperative bait detection scheme (CBDS), which aims at detecting and preventing malicious nodes launching gray hole/collaborative black hole attacks in MANETs.
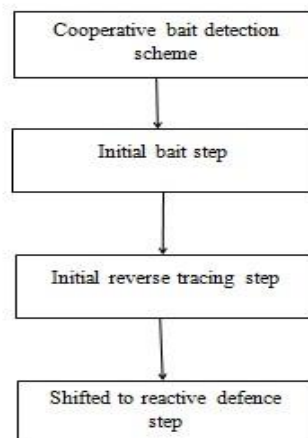
In this approach, the source node stochastically selects an adjacent node with which to cooperate, in the sense that the address of this node is used as bait destination address to bait malicious nodes to send a reply RREP message. Malicious nodes are thereby detected and prevented from participating in the routing operation, using a reverse tracing technique. In this setting, it is assumed that when a significant drop occurs in the packet delivery ratio, an alarm is sent by the destination node back to the source node to trigger the detection mechanism again. Our CBDS scheme merges the advantage of proactive detection in the initial step and therefore the superiority of reactive response at the following steps so as to scale back the resource wastage.
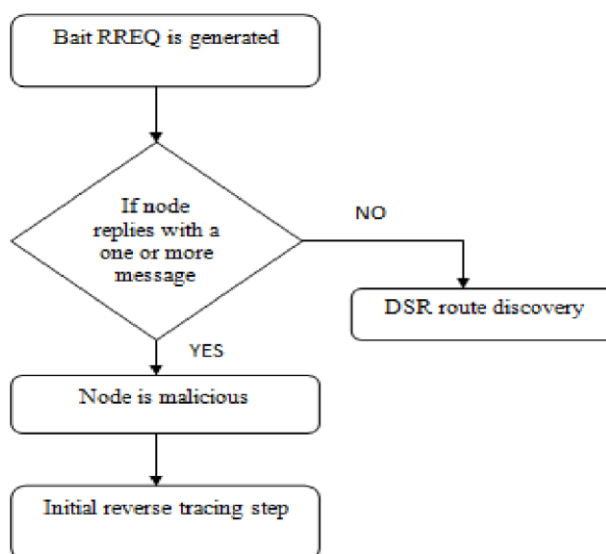


The goal of the bait phase is to simulate a malicious node to send a reply RREP by sending the bait RREQ that it has used to advertise itself as having the shortest path to the node that detains the packets that were converted. To achieve this goal, the following method is meant to get the destination address of the bait RREQ .The source node stochastically selects an adjacent node, within its one-hop neighbourhood nodes and cooperates with this node by taking its address as the destination address of the bait RREQ. First, if the neighbour node had not launched a black hole attack, then after the source node had sent out the RREQ, there would be other nodes' reply RREP in addition to that of the neighbour node. This indicates that the malicious node existed in the reply routing. The reverse tracing program in the next step would be initiated in order to detect this route. If only the neighbour node had sent the reply RREP, it means that there was no other malicious node present within the network. Hence CBDS had initiated the DSR route discovery phase.

## 4. ANALYSIS

This is defined as the average time taken for a packet to be transmitted from the source to the destination. The total delay of packets received by the destination node is $d_i$, and the number of packets received by the destination node is $pktd_i$. The average end-to-end delay of the application. Delay is the difference between the time at which the sender generated the packet and the time at which the receiver received the packet. Delay is calculated using awk script which processes the trace file and produces the result. This is defined as the total amount of data $(bi)$ that the destination receives them from the source divided by the time $(ti)$ it takes for the destination to get the final packet. The throughput is the number of bits transmitted per second. The throughput of the application traffic n. Considering such
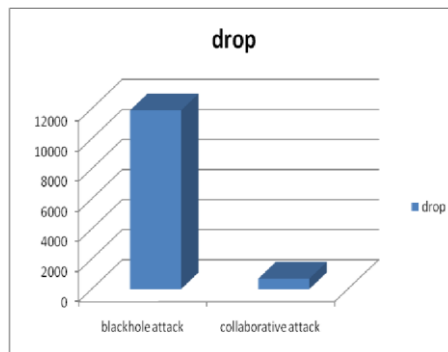
scenarios the performance metrics such as delay, throughput and packet drop are calculated. These values are calculated form the awk script in ns2 simulator.

**Table 4.1 comparison between DSR and AODV**

| Parameter/Protocol | DSR | | AODV | |
|---|---|---|---|---|
| | Scenario 1 | Scenario 2 | Scenario 1 | Scenario 2 |
| Delay | 463.054 | 338.921 | 153.184 | 156.57 |
| Throughput | 19.04 | 17.87 | 22.12 | 18.62 |
| Dropped Packets | 4582 | 9184 | 4576 | 9150 |

Awk script is one of the most prominent text-processing utility on GNU/Linux. It can solve complex text processing tasks with a few lines of code.
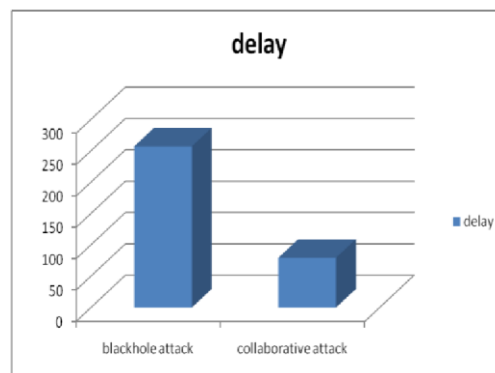


Using this script, the values for the drop, throughput and delay are generated and are plotted in the form of graph. From the above observations, AODV protocol is more efficient. Hence this routing protocol is used for further implementation.

 **CONCLUSION**

    In this work, a new mechanism called the CBDS for detecting malicious nodes in MANETs under collaborative black hole and rushing attacks. These networks are subjected to black hole  and rushing attacks. Any detected malicious node is kept in a malicious list so that all other nodes that participate to the routing of the message are alerted to stop communicating with any node in that list. In an attempt to find a lasting solution to the security challenges in MANETs, various researchers have proposed different solutions for various security issues in MANETs. Identifying a malicious node in a network

has been a reoccurring challenge. Since there is no particular line of defense, security for MANETs is still a major concern. This approach is based on using cooperative bait detection scheme to detect and prevent black hole attacks in MANETs.  This mechanism is extended against collaborative attacks such as rushing and black hole attack.

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